

PIGEON

Lukas Haas, Michal Skreta, Silas Alberti, Chelsea Finn
CVPR 2024

Geoguessr



GEOGUESSR

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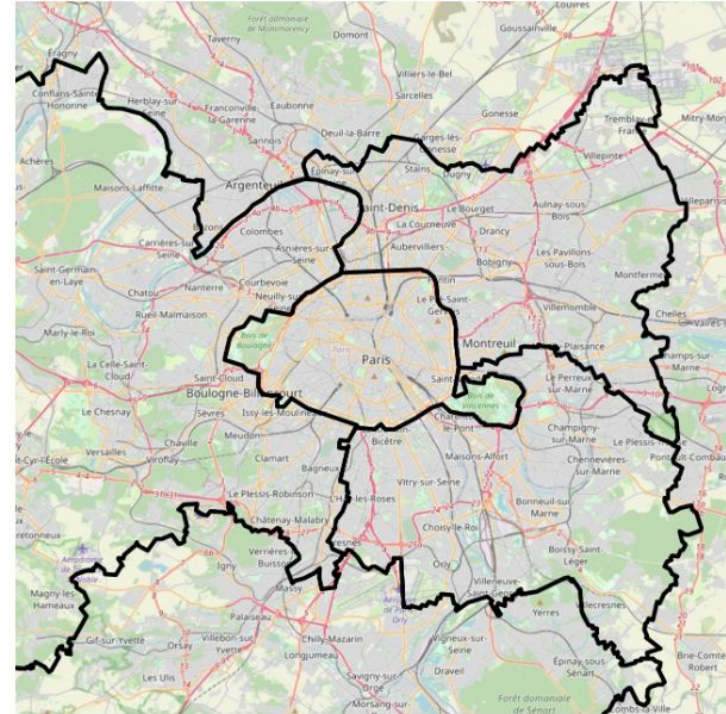
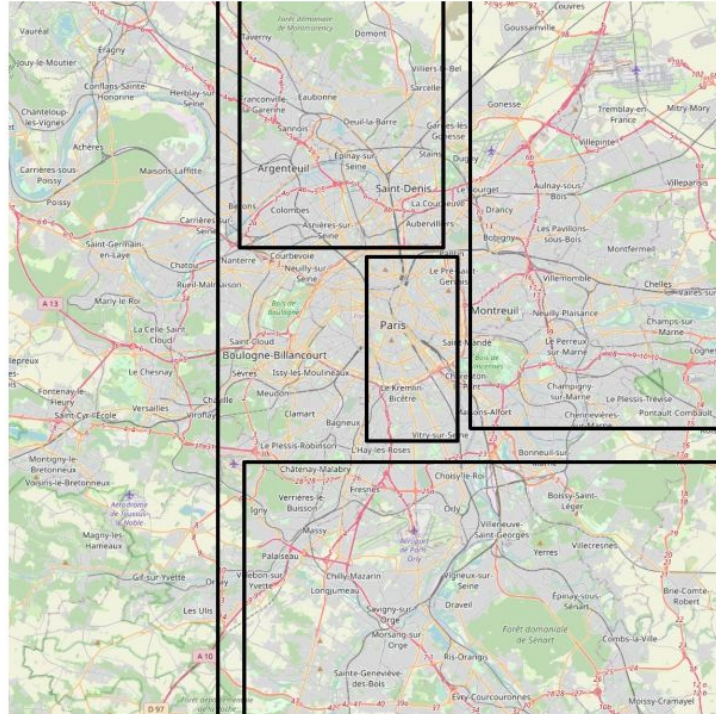
Gameplay ?

<https://www.geoguessr.com/>

Un pro :



Comment trouver une géolocalisation ?



Problème de classification : Geocells

Comment trouver une géolocalisation ?

Country

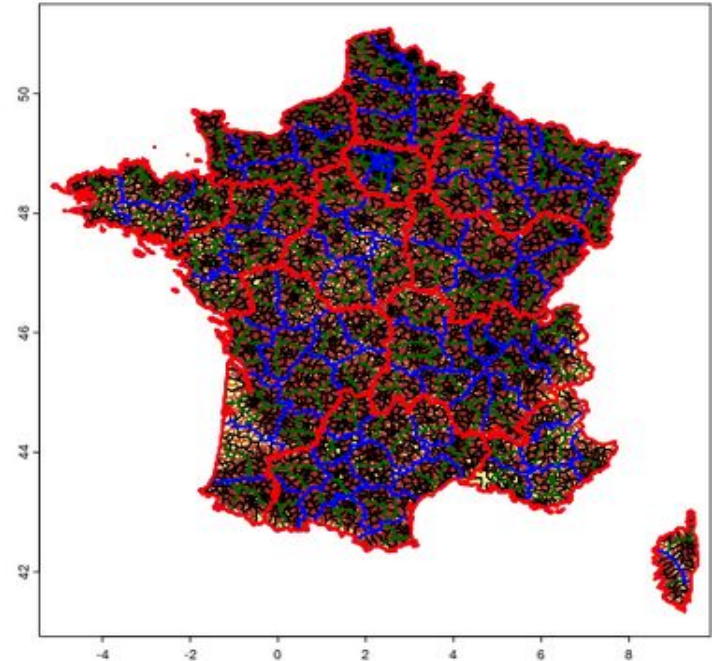
France

Geopackage

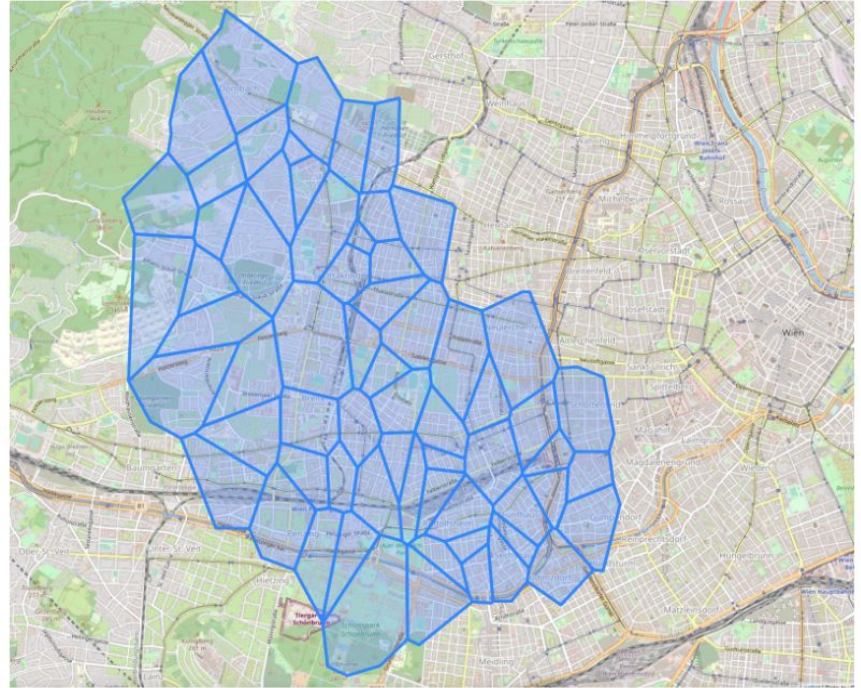
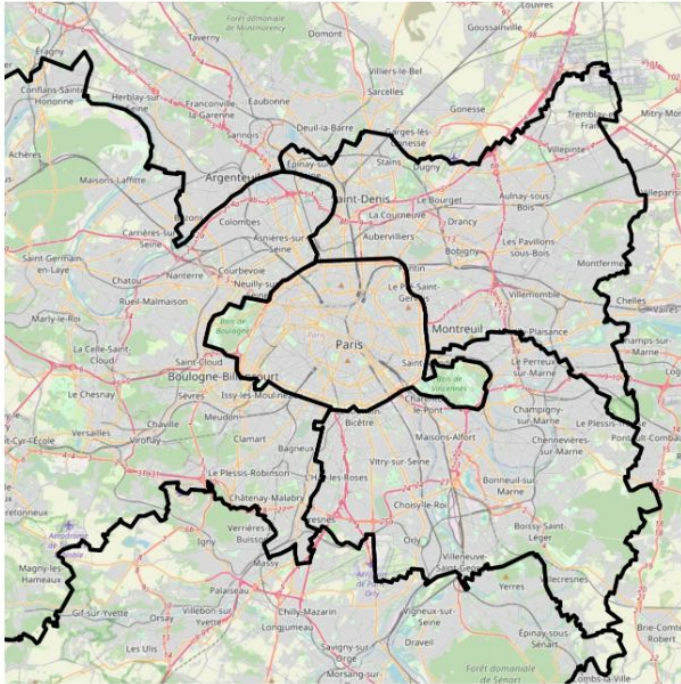
Shapefile

GeoJSON: [level-0](#), [level1](#), [level2](#), [level3](#), [level4](#)

KMZ: [level-0](#), [level1](#), [level2](#), [level3](#), [level4](#)

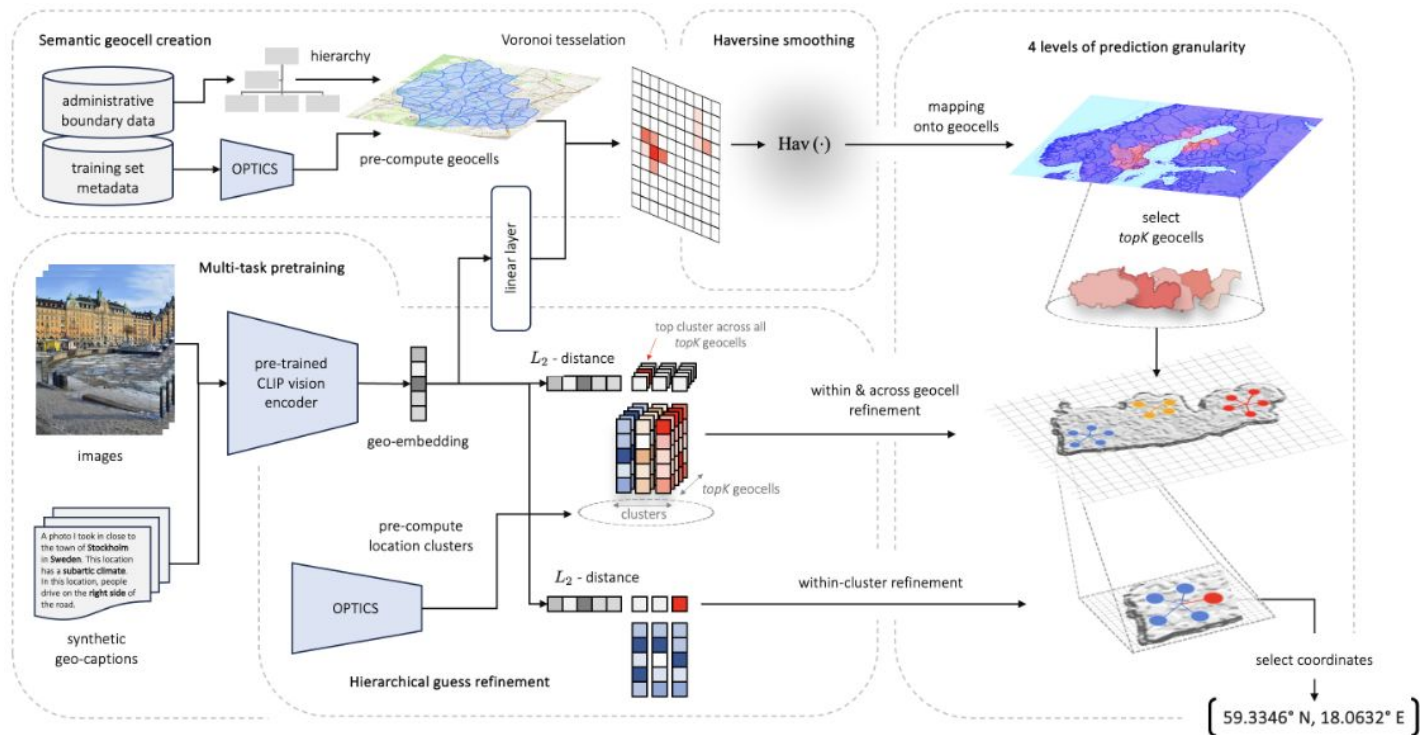


Comment trouver une géolocalisation ?



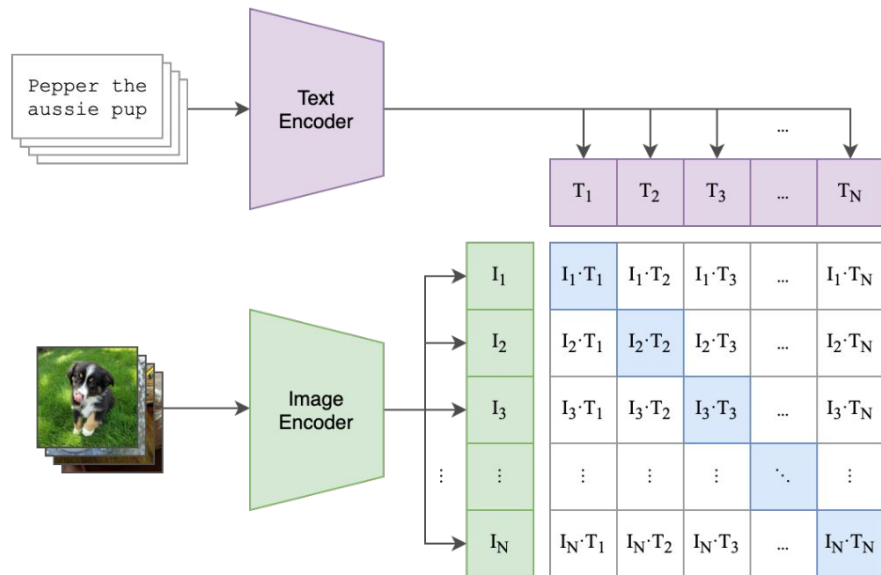
GeoCells : Régions administratives + OPTICS (clustering) + Voronoi

Overview du pipeline :

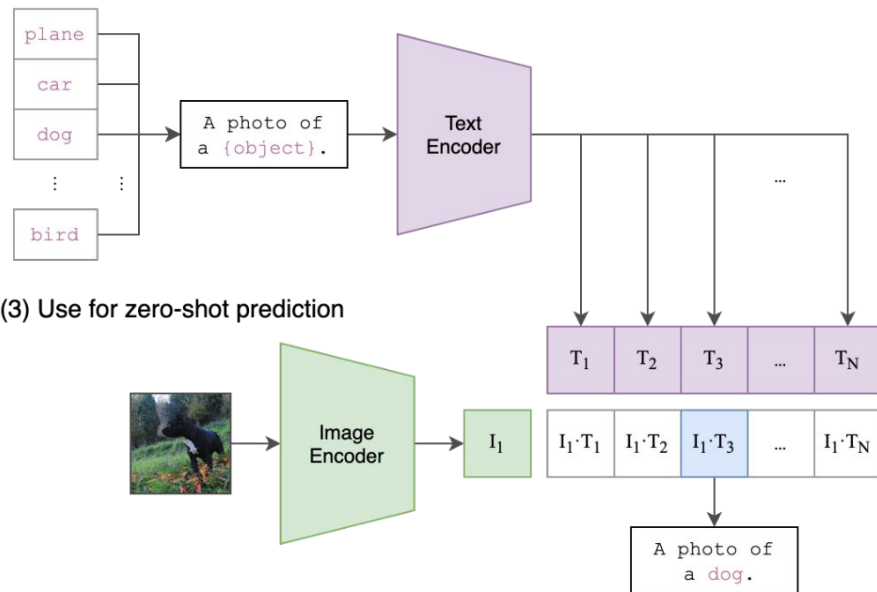


Contrastive Language-Image Pre-Training (CLIP)

(1) Contrastive pre-training



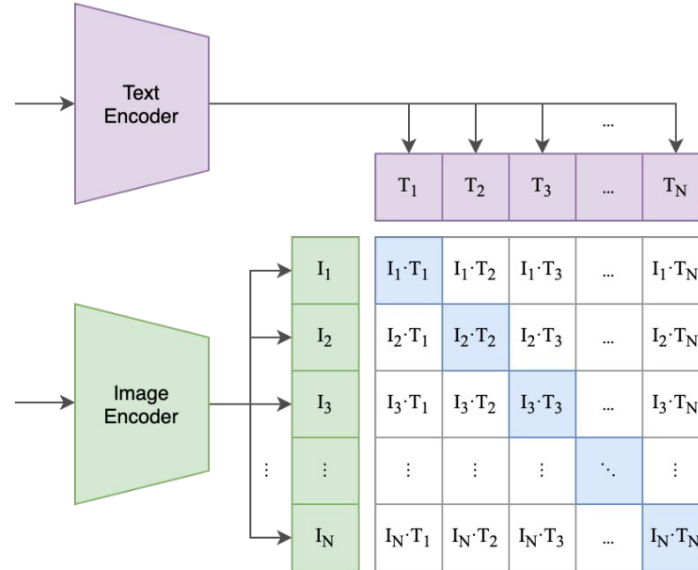
(2) Create dataset classifier from label text



Fine-Tune :

Text meta data :

- A photo in the region of Veneto, Italy
- An image facing north
- In northern hemisphere
- People drive on the left side
- The photo was taken in December



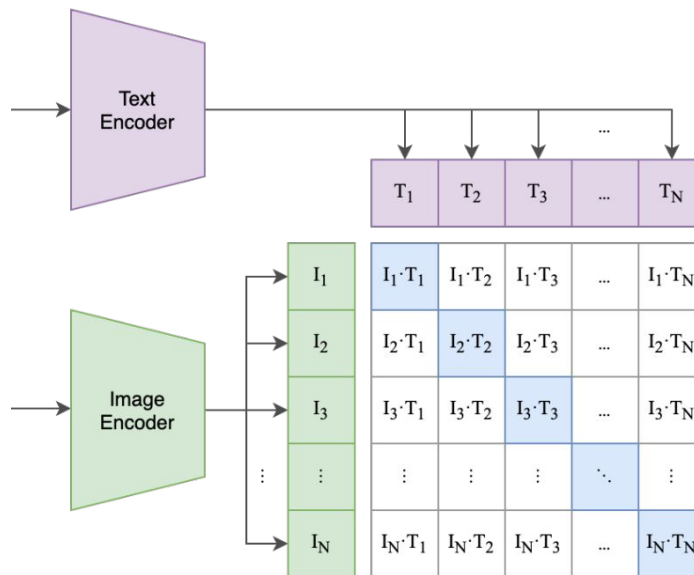
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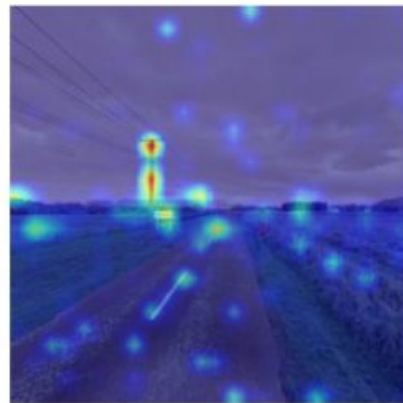
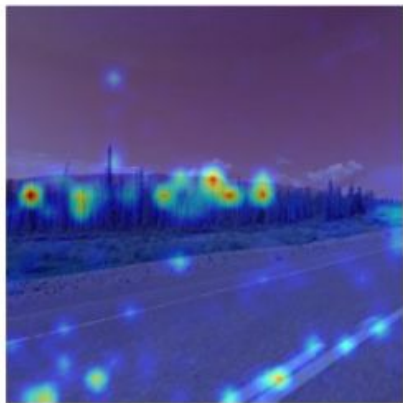
$$\mathcal{L}_n = \mathcal{L}_{n,\text{loc}} + \alpha \mathcal{L}_{n,\text{climate}} + \beta \mathcal{L}_{n,\text{month}} + \gamma \mathcal{L}_{n,\text{reg}}$$



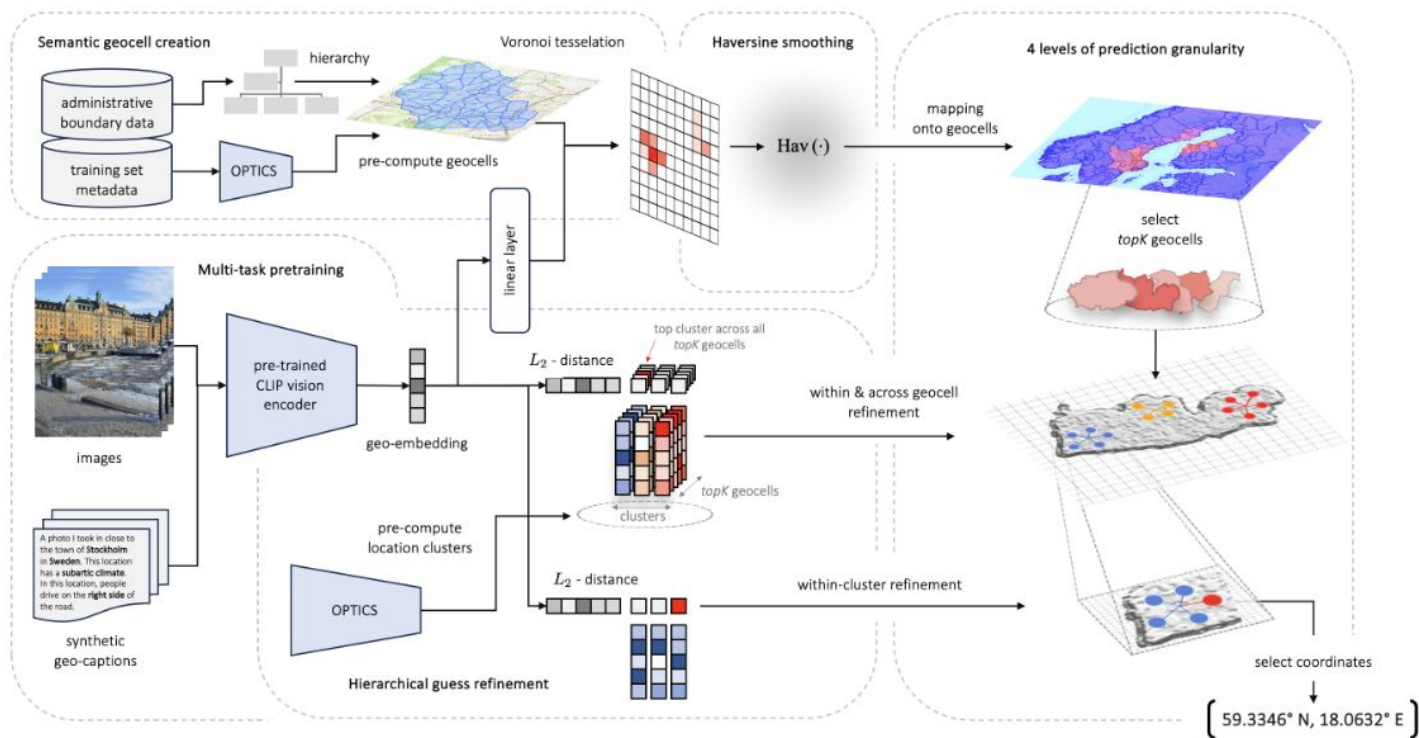
Pourquoi ces informations :

<https://geohints.com/>

Résultat du pré-entraînement



Overview du pipeline :



Raffinement : “prototype-neural networks”

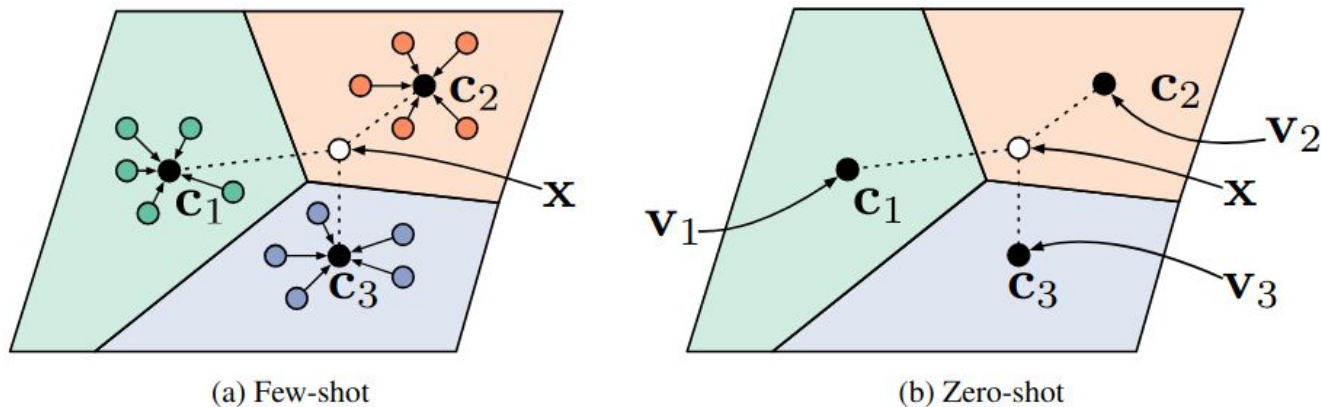


Figure 1: Prototypical networks in the few-shot and zero-shot scenarios. **Left:** Few-shot prototypes c_k are computed as the mean of embedded support examples for each class. **Right:** Zero-shot prototypes c_k are produced by embedding class meta-data v_k . In either case, embedded query points are classified via a softmax over distances to class prototypes: $p_\phi(y = k|\mathbf{x}) \propto \exp(-d(f_\phi(\mathbf{x}), c_k))$.

Raffinement : “Finding nearest neighbors”

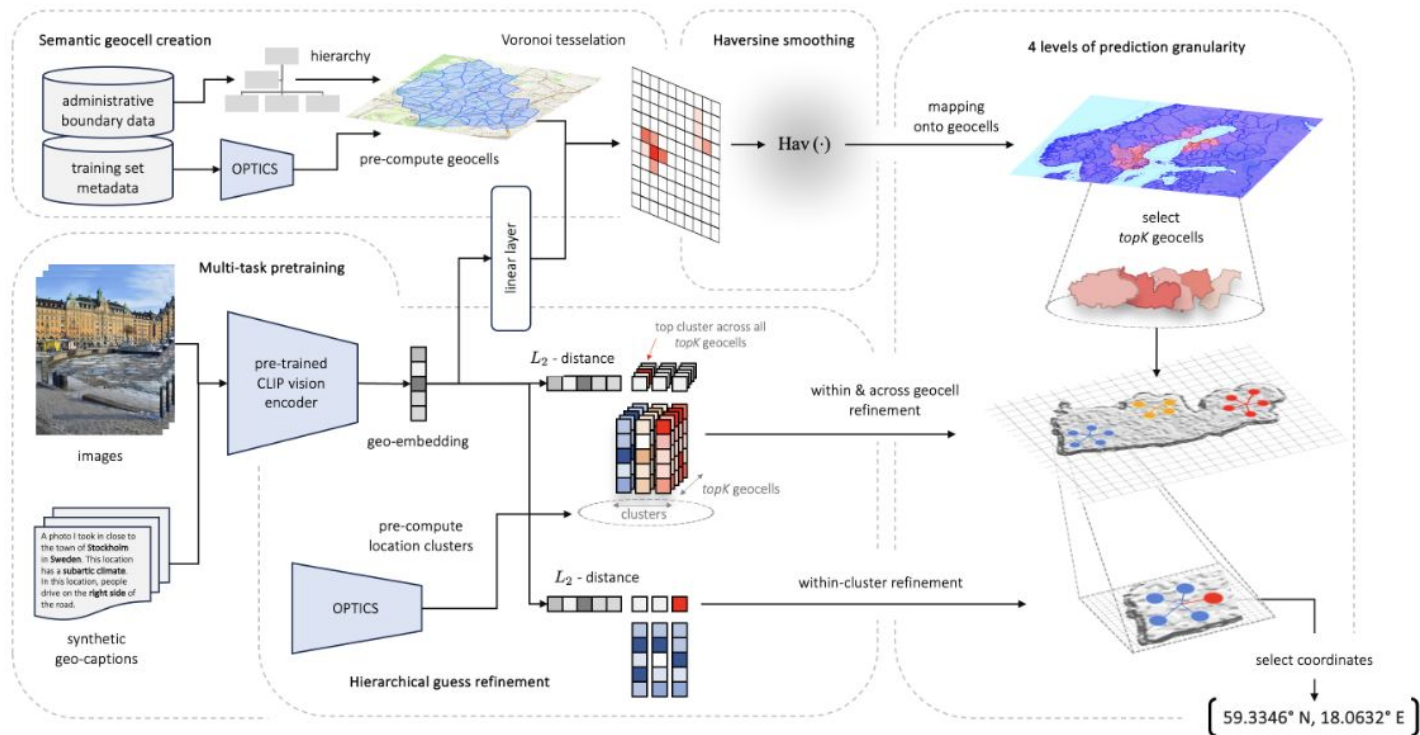
$$c^* = \arg \min_{c \in C_g} \left\| f(x) - \frac{1}{|c|} \sum_{l \in c} f(l) \right\|_2$$

f : CLIP

C_g : Candidates clusters

l : Locations within a cluster

Overview du pipeline :



Input :



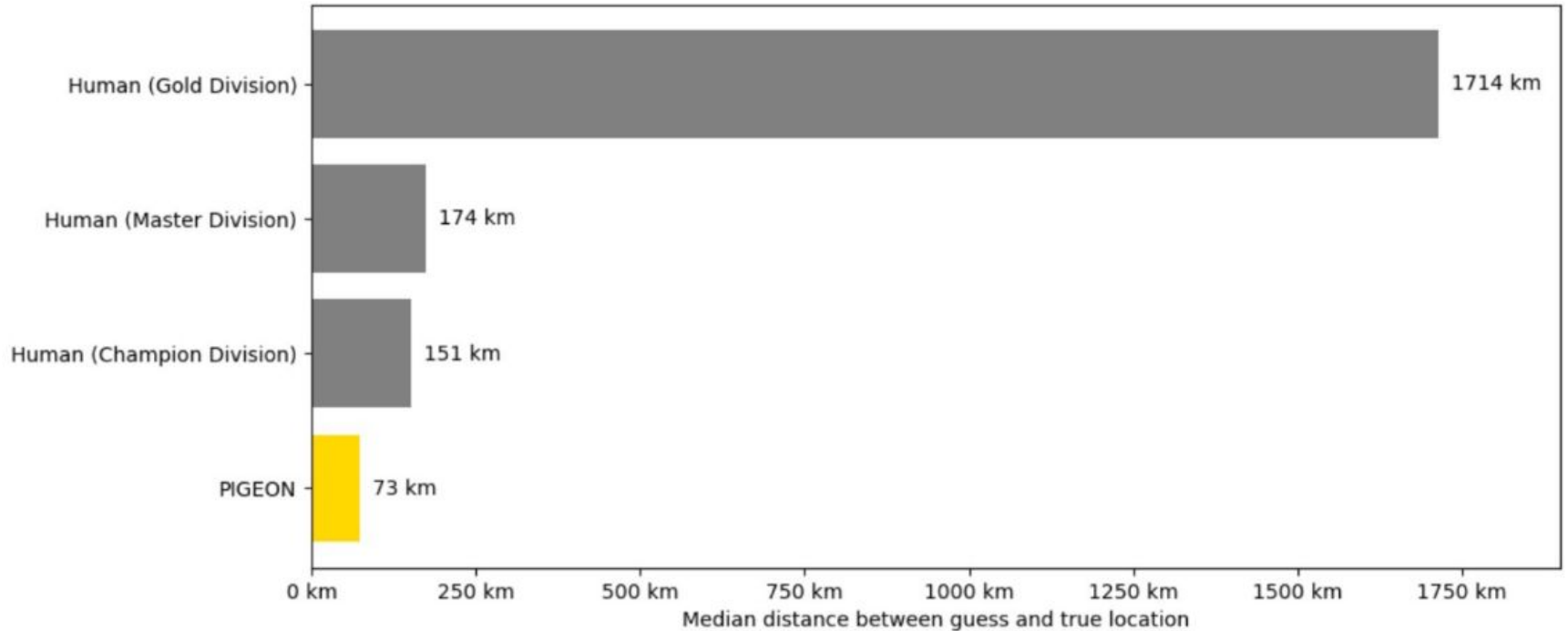
Figure 6: Four images comprising a 360-degree panorama from a location in Pegswood, England, in our dataset.

Results :

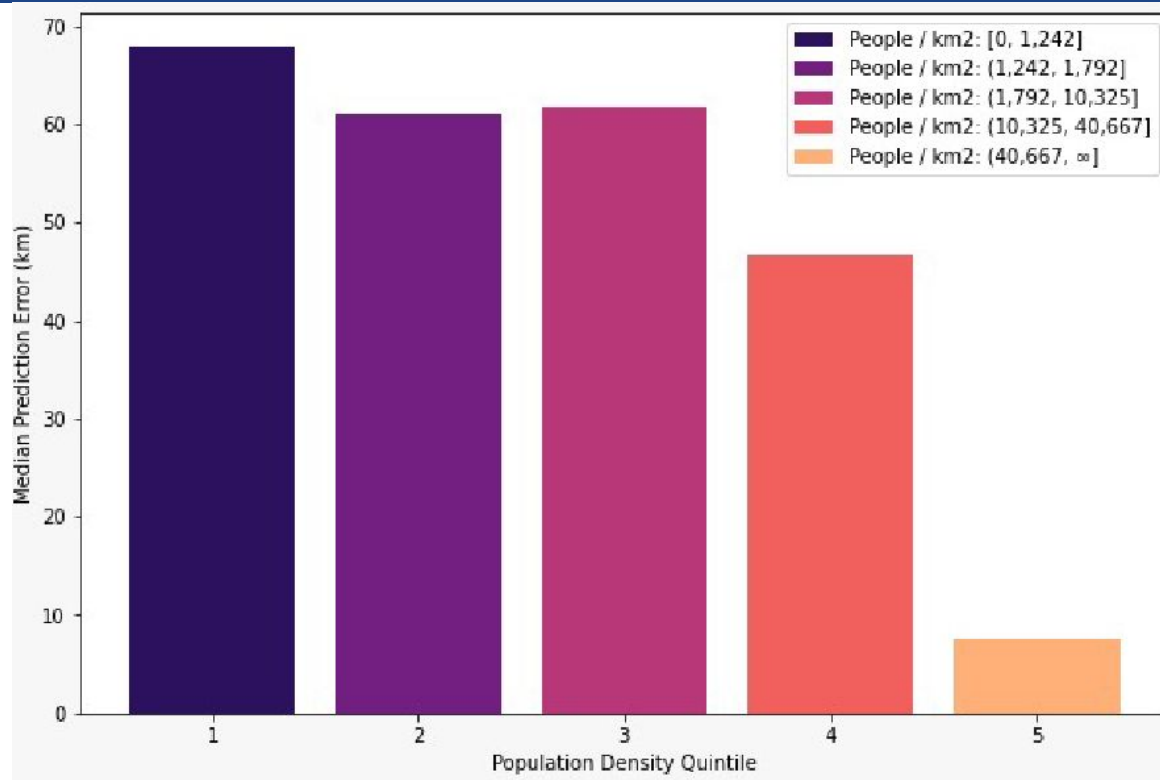
Ablation	Country Accuracy <i>%</i>	Mean Error <i>km</i>	Median Error <i>km</i>	Geoguessr Score <i>points</i>
PIGEON	91.96	251.6	44.35	4,525

Ablation	Distance (% @ km)				
	<i>Street 1 km</i>	<i>City 25 km</i>	<i>Region 200 km</i>	<i>Country 750 km</i>	<i>Continent 2,500 km</i>
PIGEON	5.36	40.36	78.28	94.52	98.56

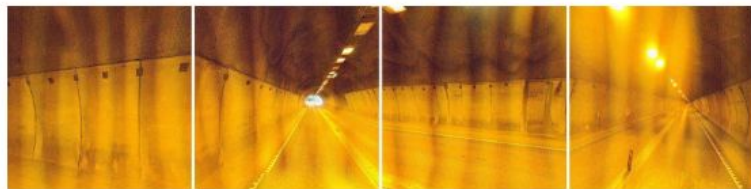
Results :



Urban vs rural :



Worst-case :



(a) Image from a tunnel.



(b) Image from a body of water.



(c) Image from a dark area.



(d) Image from a forest.



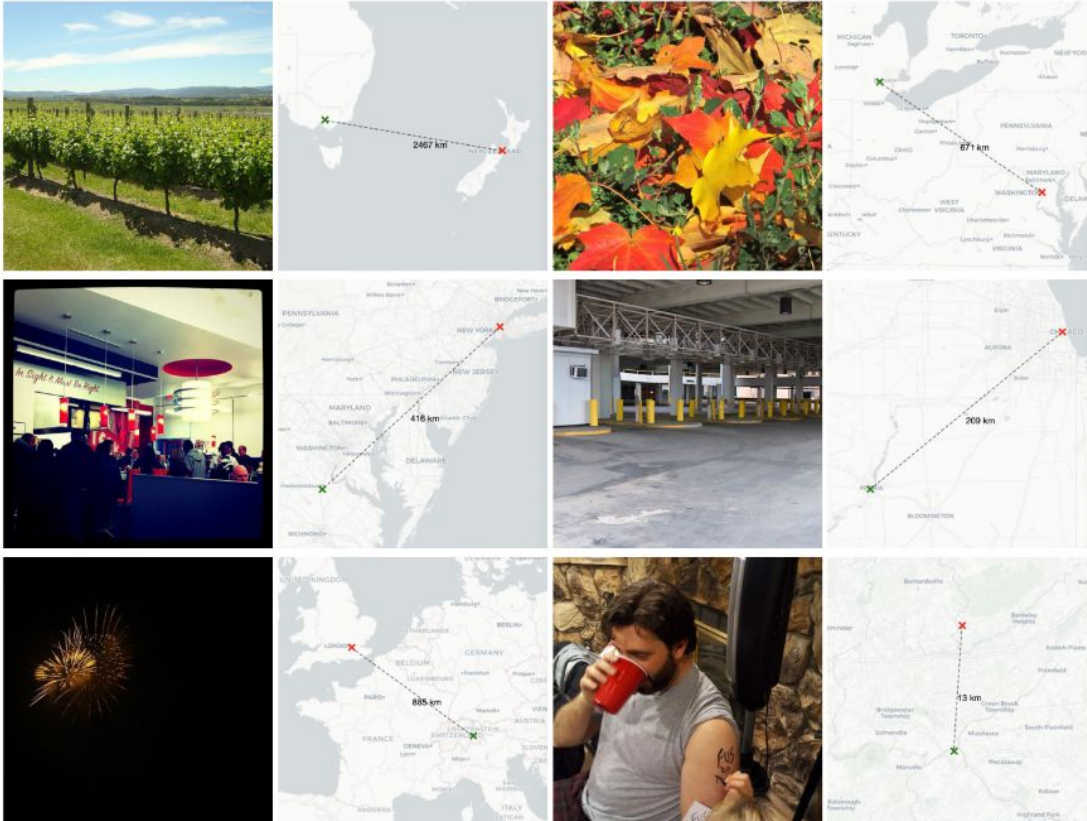
(e) Image from an indoor area.



(f) Image from a soccer stadium.

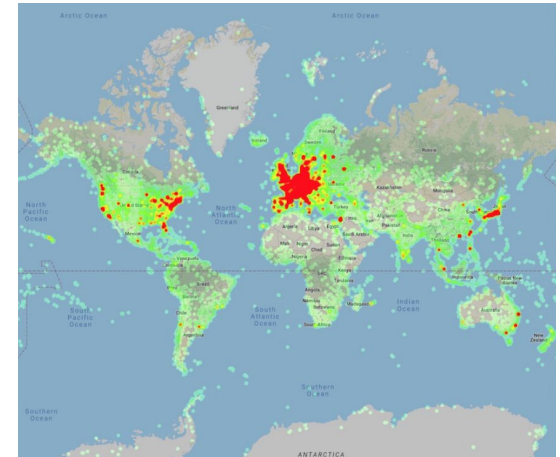
Figure 11: Examples of images for which PIGEON was the most uncertain about the correct location.

Results - PIGEOETTO :



“General image locator”:

- MediaEval database (Geolocated Flickr images)
- Google Landmarks v2



Ethics

FIN